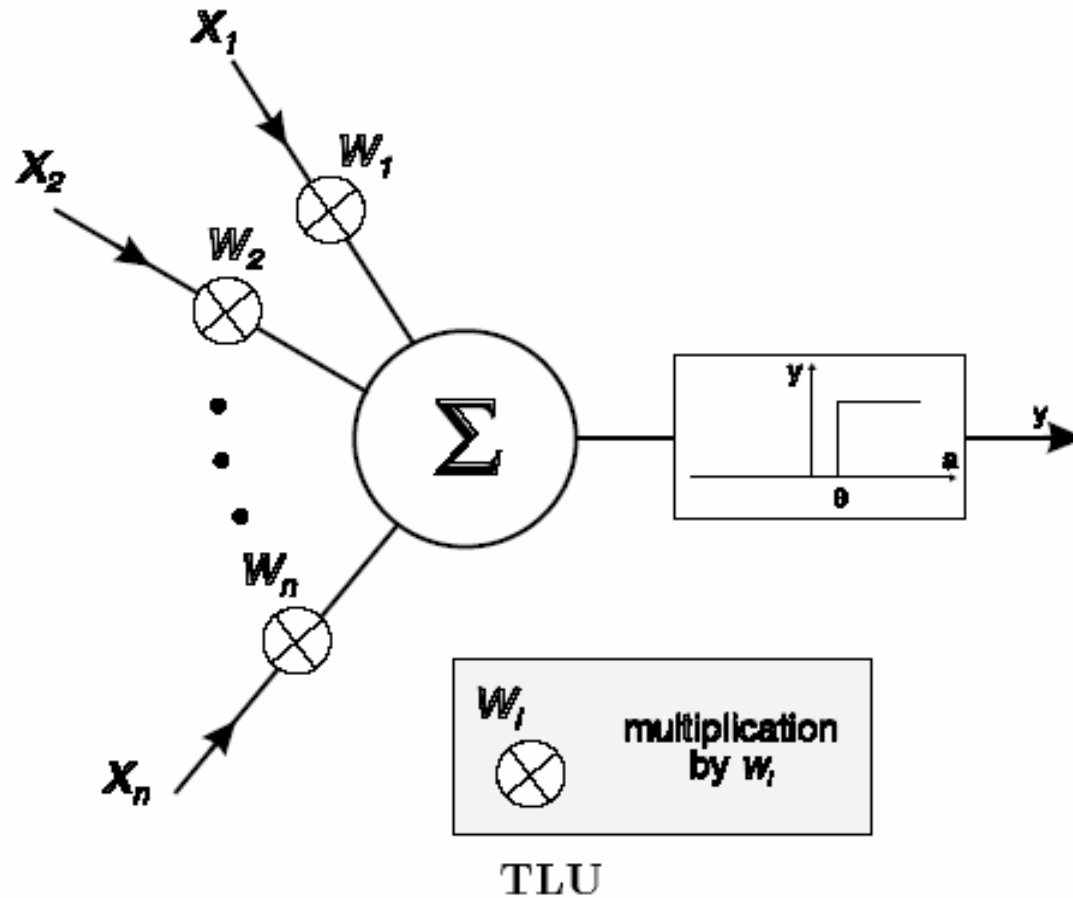


# Hybrid Intelligent Systems

## Lecture 12

Using of Genetic Algorithms for  
learning and evolution of neural  
networks

# Formal neuron by MacCulloch-Pitts

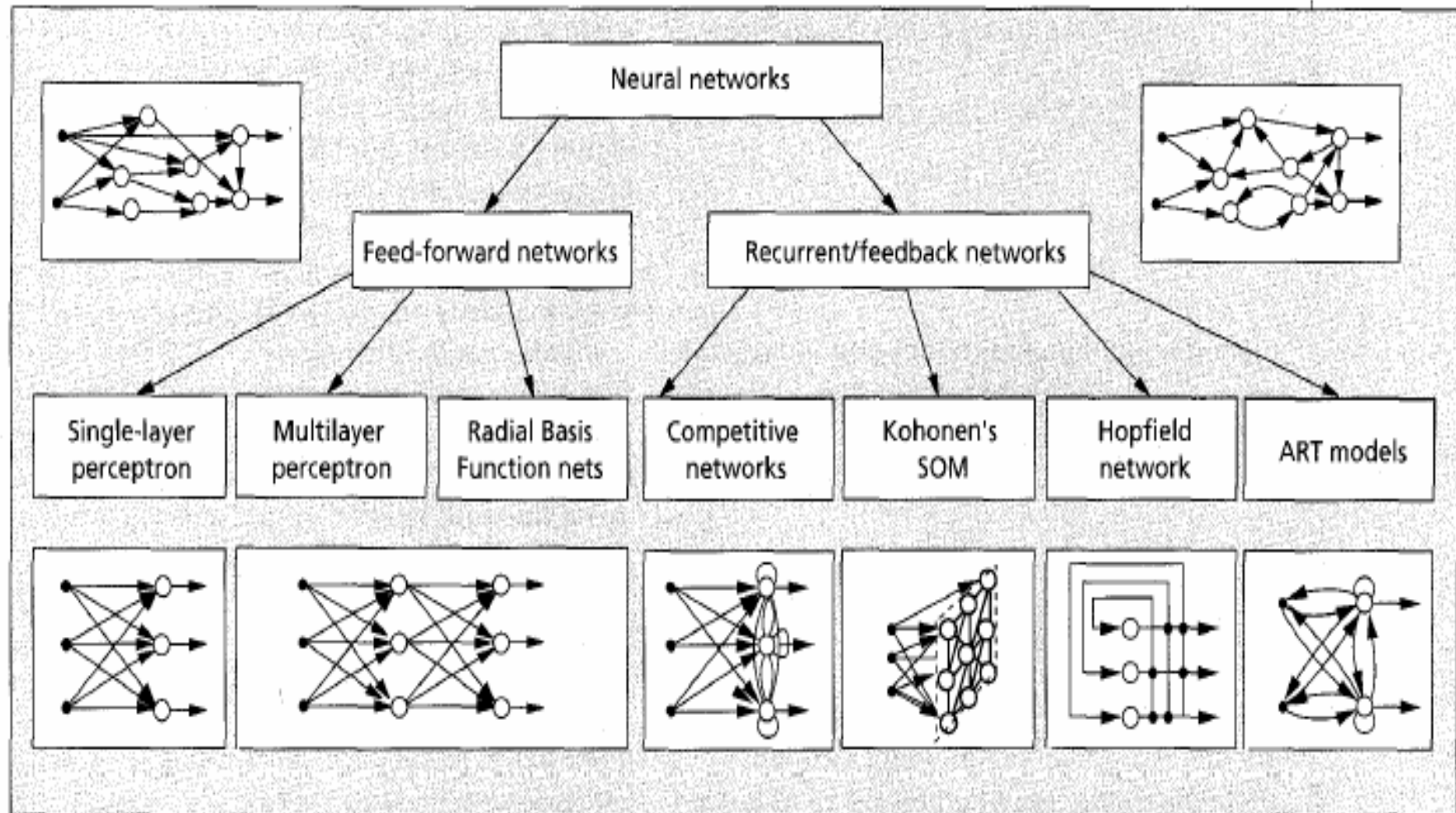


$x_i$  – binary signal

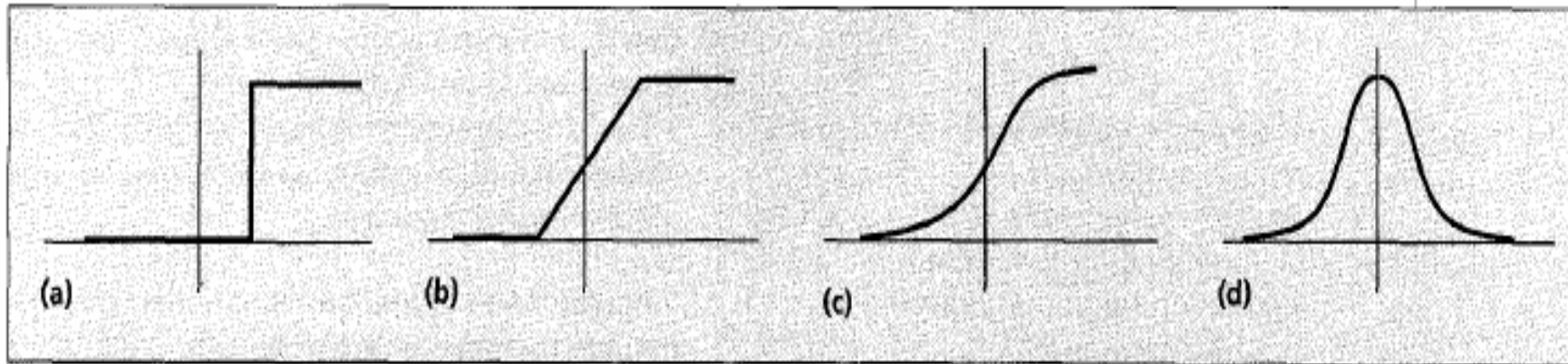
$$a = \sum_{i=1}^n w_i x_i$$

$$y = \begin{cases} 1 & \text{if } a \geq \theta \\ 0 & \text{if } a < \theta \end{cases}$$

# Taxonomy of feed-forward and recurrent networks



# Different kinds of activation function



Threshold,

piecewise linear,

sigmoid,

Gaussian

# Different approaches to learning

- Error-correction rules
  - Use error ( $d-y$ ) between desired and real output to modify the connections weights to reduce this error
- Boltzmann learning
  - To adjust the connections weights so that states of visible units satisfy a particular desired probability distribution
- Hebbian rule – strengthening connections between nodes with similar states and vice versa

$$w_{ij}(t+1) = w_{ij}(t) + \eta y_j(t) x_i(t)$$

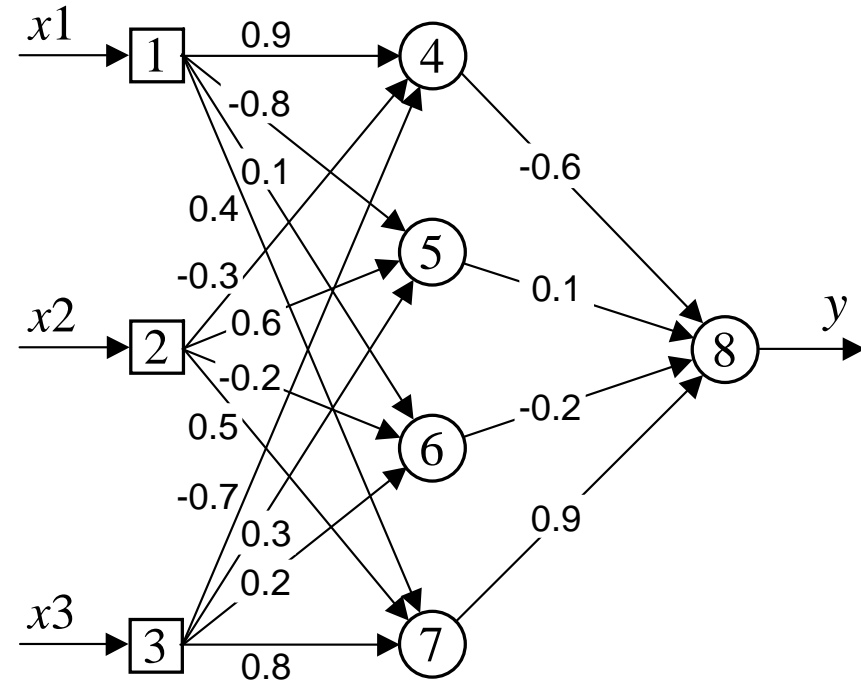
- Competitive learning rules
  - Only one output is activate in any time (*winner-take-all*)

# Using GA for learning of MLP

- For evolution of weights
- For evolution of structure (topology)

# Encoding a set of weights in a chromosome

<i>From neuron:</i>	1	2	3	4	5	6	7	8
<i>To neuron:</i> 1	0	0	0	0	0	0	0	0
2	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0
4	0.9	-0.3	-0.7	0	0	0	0	0
5	-0.8	0.6	0.3	0	0	0	0	0
6	0.1	-0.2	0.2	0	0	0	0	0
7	0.4	0.5	0.8	0	0	0	0	0
8	0	0	0	-0.6	0.1	-0.2	0.9	0



*Chromosome:*

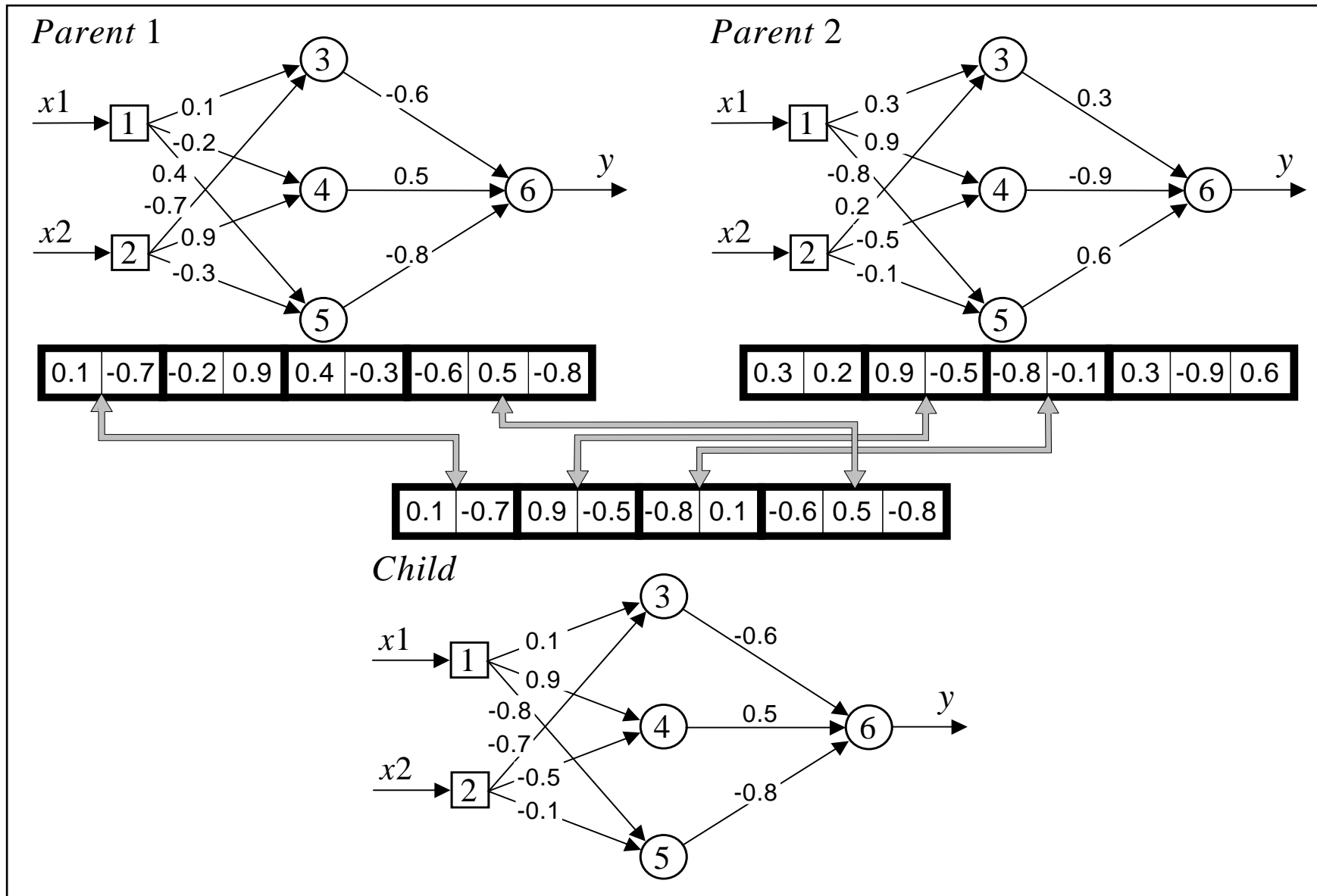
0.9	-0.3	-0.7	-0.8	0.6	0.3	0.1	-0.2	0.2	0.4	0.5	0.8	-0.6	0.1	-0.2	0.9
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- The second step is to define a fitness function for evaluating the chromosome's performance. This function must estimate the performance of a given neural network. We can apply here a simple function defined by the sum of squared errors.
- The training set of examples is presented to the network, and the sum of squared errors is calculated. The smaller the sum, the fitter the chromosome. **The genetic algorithm attempts to find a set of weights that minimises the sum of squared errors.**

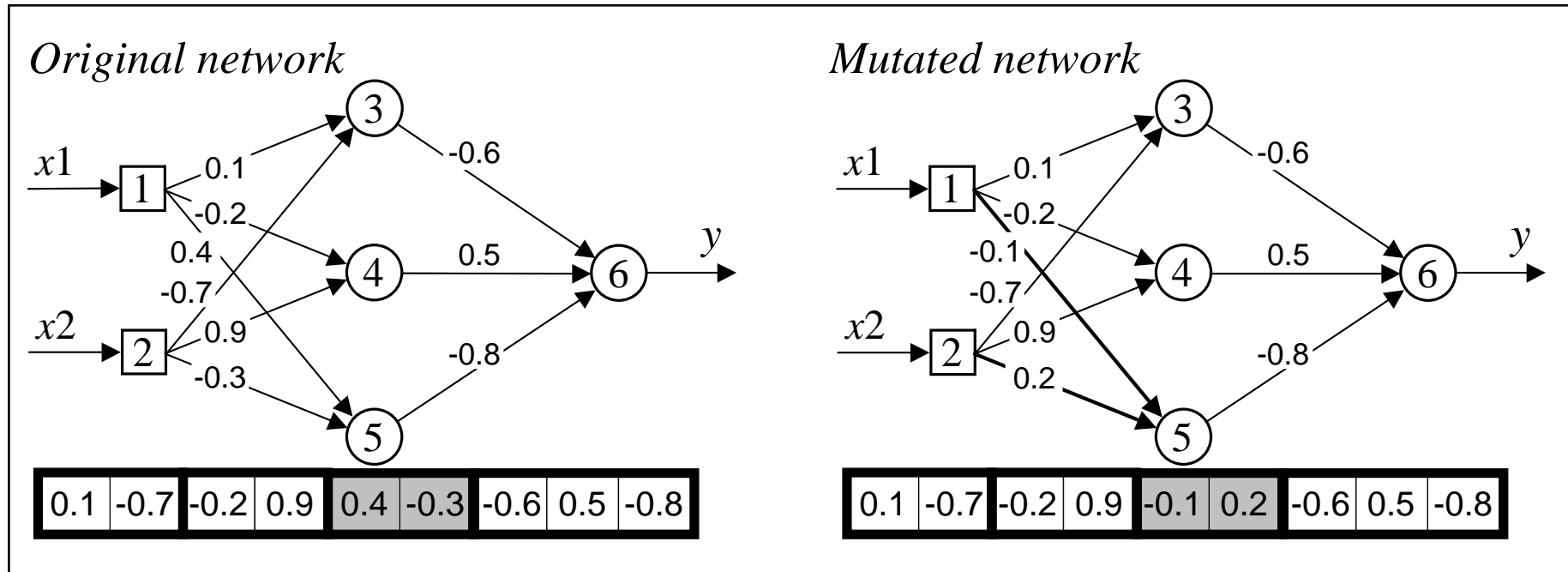


- The third step is to choose the genetic operators – crossover and mutation. A crossover operator takes two parent chromosomes and creates a single child with genetic material from both parents. Each gene in the child's chromosome is represented by the corresponding gene of the randomly selected parent.
- A mutation operator selects a gene in a chromosome and adds a small random value between  $-1$  and  $1$  to each weight in this gene.

# Crossover in weight optimisation



# Mutation in weight optimisation



# **Can genetic algorithms help us in selecting the network architecture?**

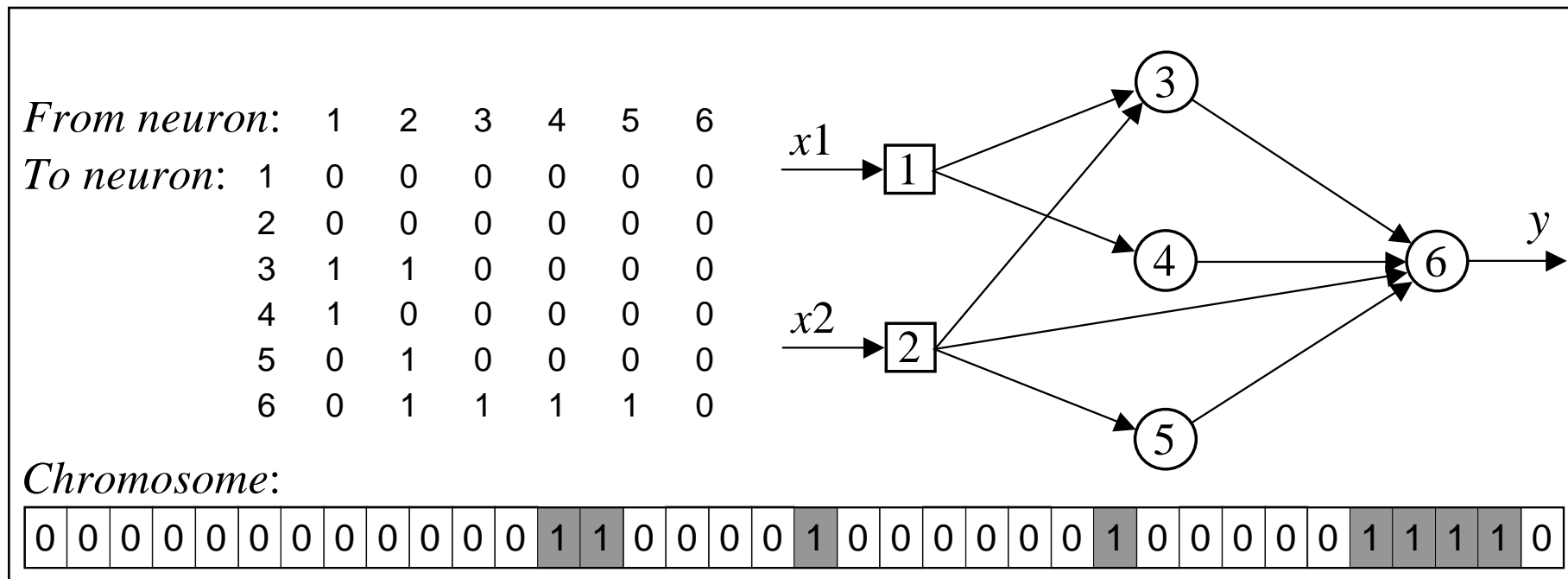
The architecture of the network (i.e. the number of neurons and their interconnections) often determines the success or failure of the application. Usually the network architecture is decided by trial and error; there is a great need for a method of automatically designing the architecture for a particular application. Genetic algorithms may well be suited for this task.

- The basic idea behind evolving a suitable network architecture is to conduct a genetic search in a population of possible architectures.
- We must first choose a method of encoding a network's architecture into a chromosome.

# Encoding the network architecture

- The connection topology of a neural network can be represented by a square connectivity matrix.
- Each entry in the matrix defines the type of connection from one neuron (column) to another (row), where 0 means no connection and 1 denotes connection for which the weight can be changed through learning.
- To transform the connectivity matrix into a chromosome, we need only to string the rows of the matrix together.

# Encoding of the network topology



# The cycle of evolving a neural network topology

